

12.3 Direction cosines and direction ratios

(1) Direction cosines: If r, s, x be the angles which a given directed line makes with the positive direction of the x, y, z co-ordinate axes respectively, then $\cos r, \cos s, \cos x$ are called the direction cosines of the given line and are generally denoted by l, m, n respectively.

Thus, $l = \cos r, m = \cos s$ and $n = \cos x, l^2 + m^2 + n^2 = 1$.

By definition, it follows that the direction cosine of the axis of x are respectively $\cos 0^\circ, \cos 90^\circ, \cos 90^\circ$ i.e., $(1, 0, 0)$. Similarly direction cosines of the axes of y and z are respectively $(0, 1, 0)$ and $(0, 0, 1)$.

(2) Direction ratios: If a, b, c are three numbers proportional to direction cosines l, m, n of a line, then a, b, c are called its direction ratios. They are also called direction numbers or direction components.

Hence by definition,

$$l = \pm \frac{a}{\sqrt{a^2 + b^2 + c^2}}, m = \pm \frac{b}{\sqrt{a^2 + b^2 + c^2}}, n = \pm \frac{c}{\sqrt{a^2 + b^2 + c^2}}$$

where the sign should be taken all positive or all negative.

Direction ratios are not unique, whereas d.c.'s are unique. i.e., $a^2 + b^2 + c^2 \neq 1$.

(3) D.c.'s and d.r.'s of a line joining two points : The direction ratios of line PQ joining $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$ are $x_2 - x_1 = a, y_2 - y_1 = b$ and $z_2 - z_1 = c$, (say).

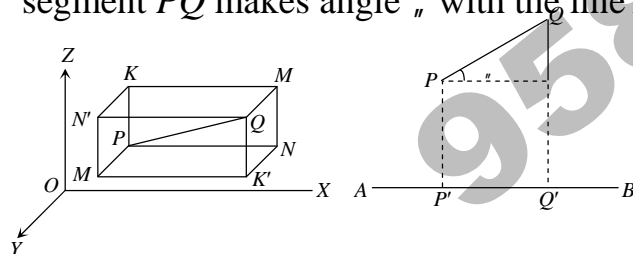
Then direction cosines are,

$$l = \frac{(x_2 - x_1)}{\sqrt{\Sigma(x_2 - x_1)^2}}, m = \frac{(y_2 - y_1)}{\sqrt{\Sigma(x_2 - x_1)^2}}, n = \frac{(z_2 - z_1)}{\sqrt{\Sigma(x_2 - x_1)^2}}$$

$$\text{i.e., } l = \frac{x_2 - x_1}{PQ}, m = \frac{y_2 - y_1}{PQ}, n = \frac{z_2 - z_1}{PQ}.$$

Projection

Projection of a line joining the points $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$ on another line whose direction cosines are l, m and n : Let PQ be a line segment where $P \equiv (x_1, y_1, z_1)$ and $Q \equiv (x_2, y_2, z_2)$ and AB be a given line with d.c.'s as l, m, n . If the line segment PQ makes angle θ with the line AB , then



Projection of PQ is $P'Q' = PQ \cos \theta$

$$= (x_2 - x_1) \cos \Gamma + (y_2 - y_1) \cos S + (z_2 - z_1) \cos X$$

$$= (x_2 - x_1)l + (y_2 - y_1)m + (z_2 - z_1)n$$

For x -axis, $l = 1, m = 0, n = 0$.

Hence, projection of PQ on x -axis $= x_2 - x_1$.

Similarly, projection of PQ on y -axis $= y_2 - y_1$ and projection of PQ on z -axis $= z_2 - z_1$.

Angle between two lines

Let θ be the angle between two straight lines AB and AC whose direction cosines are l_1, m_1, n_1 and l_2, m_2, n_2 respectively, is given by $\cos \theta = l_1 l_2 + m_1 m_2 + n_1 n_2$.

If direction ratios of two lines a_1, b_1, c_1 and a_2, b_2, c_2 are given, then angle between two lines is given by

$$\cos \theta = \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}}$$

Particular results: We have, $\sin^2 \theta = 1 - \cos^2 \theta$

$$= (l_1^2 + m_1^2 + n_1^2)(l_2^2 + m_2^2 + n_2^2) - (l_1 l_2 + m_1 m_2 + n_1 n_2)^2$$

$$= (l_1 m_2 - l_2 m_1)^2 + (m_1 n_2 - m_2 n_1)^2 + (n_1 l_2 - n_2 l_1)^2$$

$$\Rightarrow \sin \theta = \pm \sqrt{\Sigma(l_1 m_2 - l_2 m_1)^2}, \text{ which is known as Lagrange's identity.}$$

The value of $\sin \theta$ can easily be obtained by,

$$\sin \theta = \sqrt{\left| \begin{matrix} l_1 & m_1 \\ l_2 & m_2 \end{matrix} \right|^2 + \left| \begin{matrix} m_1 & n_1 \\ n_2 & l_2 \end{matrix} \right|^2 + \left| \begin{matrix} n_1 & l_1 \\ l_2 & m_2 \end{matrix} \right|^2}$$

If a_1, b_1, c_1 and a_2, b_2, c_2 are d.r.'s of two given lines, then angle θ between them is given by $\sin \theta = \frac{\sqrt{\Sigma(a_1 b_2 - a_2 b_1)^2}}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}}$

Condition of perpendicularity: If the given lines are perpendicular, then $\theta = 90^\circ$ i.e., $\cos \theta = 0$

$$\Rightarrow l_1 l_2 + m_1 m_2 + n_1 n_2 = 0 \text{ or } a_1 a_2 + b_1 b_2 + c_1 c_2 = 0$$

Condition of parallelism: If the given lines are parallel, then $\theta = 0^\circ$ i.e., $\sin \theta = 0 \Rightarrow \frac{l_1}{l_2} = \frac{m_1}{m_2} = \frac{n_1}{n_2}$.

$$\text{Similarly, } \frac{a_1}{a_2} = \frac{b_1}{b_2} = \frac{c_1}{c_2}.$$